



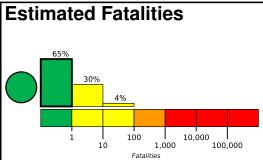


PAGER Version 4

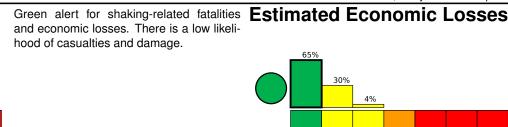
Created: 3 weeks, 0 days after earthquake

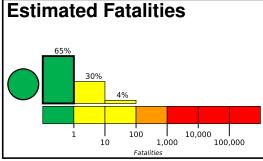
M 5.6, 123 km N of Neiafu, Tonga

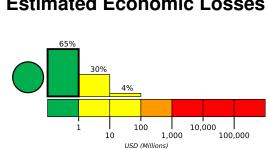
Origin Time: 2023-10-27 03:02:24 UTC (Thu 15:02:24 local) Location: 17.5550° S 173.7630° W Depth: 35.0 km



and economic losses. There is a low likeli-





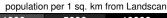


Estimated Population Exposed to Earthquake Shaking

| ESTIMATED POPULATION EXPOSURE (k=x1000) | | _* | 15k | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
|--|--------------------------|----------|--------|-------|----------|----------|-------------|------------|----------|----------|
| ESTIMATED MODIFIED MERCALLI INTENSITY | | I | 11-111 | IV | V | VI | VII | VIII | IX | X+ |
| PERCEIVE | SHAKING | Not felt | Weak | Light | Moderate | Strong | Very Strong | Severe | Violent | Extreme |
| POTENTIAL | Resistant Structures | None | None | None | V. Light | Light | Moderate | Mod./Heavy | Heavy | V. Heavy |
| DAMAGE | Vulnerable Structures | None | None | None | Light | Moderate | Mod./Heavy | Heavy | V. Heavy | V. Heavy |

^{*}Estimated exposure only includes population within the map area.

Population Exposure





Overall, the population in this region resides in structures that are highly vulnerable to earthquake shaking, though some resistant structures exist. The predominant vulnerable building types are unknown/miscellaneous types and wood construction.

Historical Earthquakes

Structures

| Date | Dist. | Mag. | Max | Shaking | |
|------------|-------|------|----------|---------|--|
| (UTC) | (km) | | MMI(#) | Deaths | |
| 2006-09-28 | 217 | 6.9 | IV(197k) | 0 | |
| 1999-01-05 | 106 | 5.9 | VII(15k) | _ | |
| 2006-05-03 | 290 | 8.0 | VIII(7k) | 0 | |

Selected City Exposure

| ı | nom decivames.org | | | | | |
|---|-------------------|--------|------------|--|--|--|
| l | MMI | City | Population | | | |
| l | Ш | Hihifo | 1k | | | |
| | Ш | Neiafu | 4k | | | |

bold cities appear on map.

(k = x1000)

PAGER content is automatically generated, and only considers losses due to structural damage. Limitations of input data, shaking estimates, and loss models may add uncertainty.